

A Quadratically Convergent Algorithm for Structured Low-Rank Approximation

Éric Schost, Pierre-Jean Spaenlehauer

Western University, London, Canada
Max Planck Institute for Mathematics, Bonn, Germany

RAIM
IHP, Nov. 20, 2013

Problem Statement

$p, q, r \in \mathbb{N}$

E a **linear/affine subspace** of $p \times q$ matrices with real entries

For $(M_{i,j})$ a $p \times q$ matrix, $\|M\|_F = \sqrt{\sum_{i,j} M_{i,j}^2}$

$\langle M_1, M_2 \rangle = \text{trace}(M_1 \cdot M_2^\top)$

Problem Statement

$p, q, r \in \mathbb{N}$

E a linear/affine subspace of $p \times q$ matrices with real entries

For $(M_{i,j})$ a $p \times q$ matrix, $\|M\|_F = \sqrt{\sum_{i,j} M_{i,j}^2}$

$\langle M_1, M_2 \rangle = \text{trace}(M_1 \cdot M_2^T)$

Structured Low-Rank Approximation

Given $M \in E$, compute a matrix $\hat{M} \in E$ such that

- $\text{Rank}(\hat{M}) \leq r$;
- $\|M - \hat{M}\|_F$ is **small**.

Problem Statement

$$p, q, r \in \mathbb{N}$$

E a linear/affine subspace of $p \times q$ matrices with real entries

For $(M_{i,j})$ a $p \times q$ matrix, $\|M\|_F = \sqrt{\sum_{i,j} M_{i,j}^2}$

$$\langle M_1, M_2 \rangle = \text{trace}(M_1 \cdot M_2^T)$$

Structured Low-Rank Approximation

Given $M \in E$, compute a matrix $\hat{M} \in E$ such that

- $\text{Rank}(\hat{M}) \leq r$;
- $\|M - \hat{M}\|_F$ is **small**.

"Behind every linear data modeling problem there is a (hidden) low-rank approximation problem: the model imposes relations on the data which render a matrix constructed from exact data rank deficient."

Markovsky, 08

- $E = \text{Sylvester matrices} \rightsquigarrow \text{univariate approximate GCD}$

$$\begin{bmatrix} a_3 & 0 & b_2 & 0 & 0 \\ a_2 & a_3 & b_1 & b_2 & 0 \\ a_1 & a_2 & b_0 & b_1 & b_2 \\ a_0 & a_1 & 0 & b_0 & b_1 \\ 0 & a_0 & 0 & 0 & b_0 \end{bmatrix}$$

Examples and applications

- $E =$ **Sylvester matrices** \rightsquigarrow univariate approximate GCD
- $E =$ **Hankel matrices** \rightsquigarrow denoising, signal processing

$$\begin{bmatrix} a & b & c & d & e \\ b & c & d & e & f \\ c & d & e & f & g \\ d & e & f & g & h \\ e & f & g & h & i \end{bmatrix}$$

Examples and applications

- $E =$ **Sylvester matrices** \rightsquigarrow univariate approximate GCD
- $E =$ **Hankel matrices** \rightsquigarrow denoising, signal processing
- $E =$ **affine coordinate spaces** \rightsquigarrow matrix completion

$$\begin{bmatrix} 3 & ? & ? & 5 & 5 \\ 1 & 2 & 3 & 2 & ? \\ 10 & 4 & ? & 9 & -4 \\ 6 & ? & 3 & 9 & 10 \\ ? & 5 & -2 & ? & 9 \end{bmatrix}$$

Examples and applications

- $E =$ **Sylvester matrices** \rightsquigarrow univariate approximate GCD
- $E =$ **Hankel matrices** \rightsquigarrow denoising, signal processing
- $E =$ **affine coordinate spaces** \rightsquigarrow matrix completion
- $E =$ **Ruppert matrices** \rightsquigarrow multivariate factorization

$$\begin{bmatrix} 0 & -2 & -a & 0 & -2b & -d \\ -1 & 0 & c & -b & 0 & e \\ a & 2c & 0 & d & 2e & 0 \\ 0 & 0 & 0 & 1 & a & c \\ 0 & 0 & 0 & -b & -d & -e \end{bmatrix}$$

$XY^2 + aXY + bY^2 + cX + dY + e \in \mathbb{C}[X, Y]$ factors \Leftrightarrow rank ≤ 4

\mathcal{D}_r : manifold of $p \times q$ matrices of **rank r**
 E : linear/affine subspace of $p \times q$ matrices

Algorithm NewtonSLRA

NewtonSLRA: iterative algorithm with proven local **quadratic convergence** under mild **transversality assumptions**.

\mathcal{D}_r : manifold of $p \times q$ matrices of **rank r**
 E : linear/affine subspace of $p \times q$ matrices

Algorithm NewtonSLRA

NewtonSLRA: iterative algorithm with proven local **quadratic convergence** under mild **transversality assumptions**.

More precisely: for any smooth point $\zeta \in \mathcal{D}_r \cap E$ where \mathcal{D}_r and E **intersect transversely**, there exists a small neighborhood $U \ni \zeta$ such that for any input matrix $M_0 \in U$,

- the sequence of iterates M_1, M_2, \dots **converges quadratically** towards $M_\infty \in \mathcal{D}_r \cap E$, i.e.
$$\|M_i - M_\infty\| \leq (1/2)^{2^i - 1} \|M_0 - M_\infty\|$$

\mathcal{D}_r : manifold of $p \times q$ matrices of **rank r**
 E : linear/affine subspace of $p \times q$ matrices

Algorithm NewtonSLRA

NewtonSLRA: iterative algorithm with proven local **quadratic convergence** under mild **transversality assumptions**.

More precisely: for any smooth point $\zeta \in \mathcal{D}_r \cap E$ where \mathcal{D}_r and E **intersect transversely**, there exists a small neighborhood $U \ni \zeta$ such that for any input matrix $M_0 \in U$,

- the sequence of iterates M_1, M_2, \dots **converges quadratically** towards $M_\infty \in \mathcal{D}_r \cap E$, i.e.
$$\|M_i - M_\infty\| \leq (1/2)^{2^i - 1} \|M_0 - M_\infty\|$$
- Let \hat{M} be the **nearest solution**;
then
$$\|M_\infty - \hat{M}\| = O(\text{dist}(M_0, \mathcal{D}_r \cap E)^2).$$

Eckart-Young theorem

Let $M = U \cdot S \cdot V^T$ be the **Singular Value Decomposition** of M , where $S = \text{Diag}(\sigma_1, \dots, \sigma_q)$ with $\sigma_1 \geq \dots \geq \sigma_q$.

Set $\widehat{S} = \text{Diag}(\sigma_1, \dots, \sigma_r, 0, \dots, 0)$.

Then $\widehat{M} = U \cdot \widehat{S} \cdot V^T$ is the rank r matrix which **minimizes the Frobenius distance to M** .

Eckart-Young theorem

Let $M = U \cdot S \cdot V^T$ be the **Singular Value Decomposition** of M , where $S = \text{Diag}(\sigma_1, \dots, \sigma_q)$ with $\sigma_1 \geq \dots \geq \sigma_q$.

Set $\widehat{S} = \text{Diag}(\sigma_1, \dots, \sigma_r, 0, \dots, 0)$.

Then $\widehat{M} = U \cdot \widehat{S} \cdot V^T$ is the rank r matrix which **minimizes the Frobenius distance to M** .

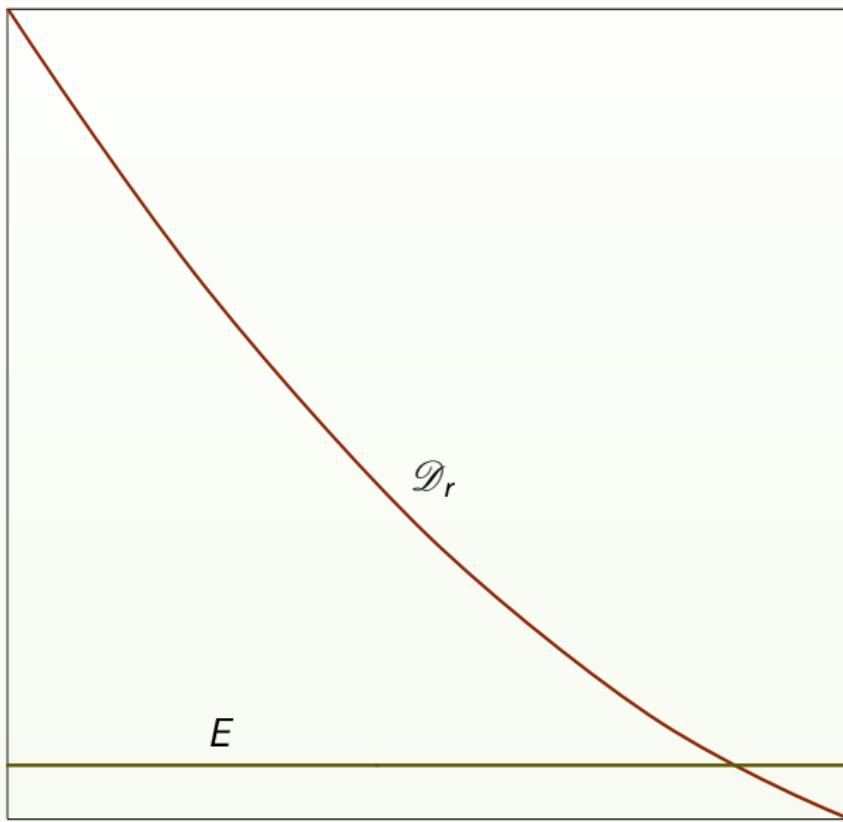
Cadzow's algorithm (*Cadzow, 88, Lewis/Malick 08*):

- project on \mathcal{D}_r (the **manifold** of matrices of rank r) with **SVD**;
- project back on E .

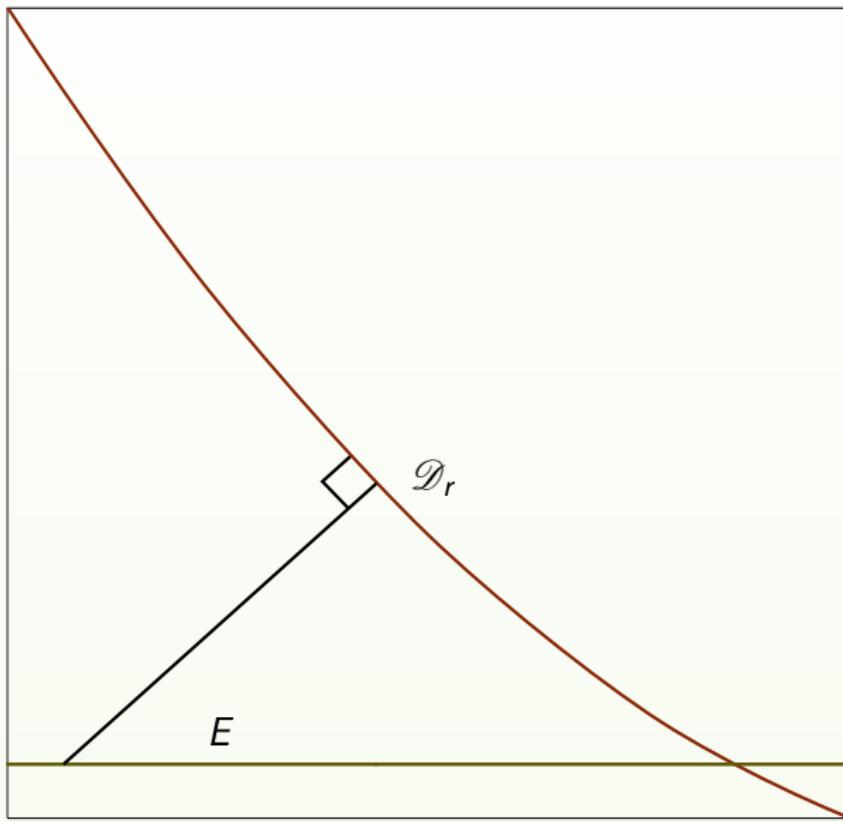
Converges **linearly** towards a point in $\mathcal{D}_r \cap E$.

Does not converge to the **nearest solution**.

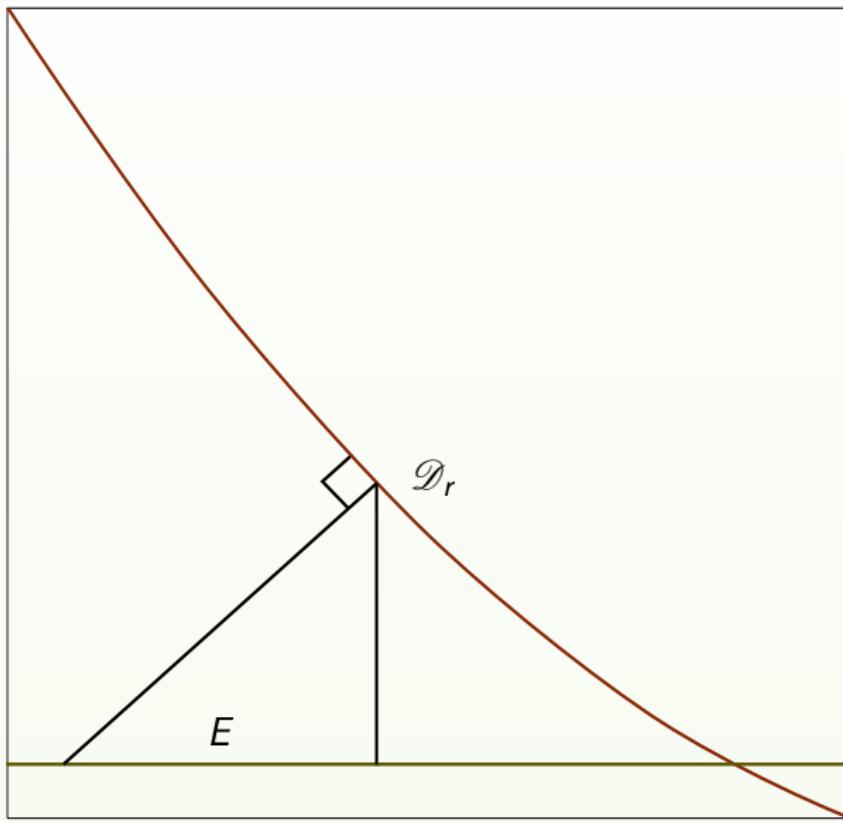
Cadzow's algorithm



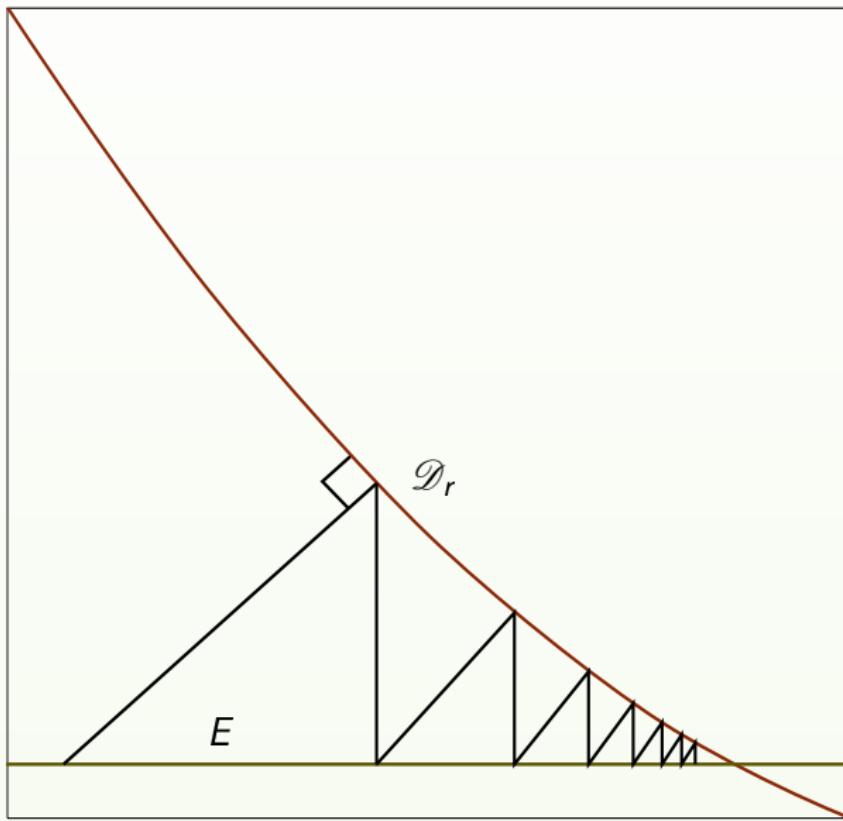
Cadzow's algorithm



Cadzow's algorithm



Cadzow's algorithm



Newton's method

Classical **Newton's method** for $f : \mathbb{R}^n \rightarrow \mathbb{R}^n$

$$N_f(x) = Df(x)^{-1}(f(x)).$$

Quadratic convergence when Df is locally invertible.

Newton's method

Classical **Newton's method** for $f : \mathbb{R}^n \rightarrow \mathbb{R}^n$

$$N_f(x) = Df(x)^{-1}(f(x)).$$

Quadratic convergence when Df is locally invertible.

Newton's method for underdetermined systems:

$$f : \mathbb{R}^m \rightarrow \mathbb{R}^n, N_f(x) = Df(x)^\dagger(f(x)).$$

Df^\dagger : **Moore-Penrose pseudo-inverse**.

Newton's method

Classical **Newton's method** for $f : \mathbb{R}^n \rightarrow \mathbb{R}^n$

$$N_f(x) = Df(x)^{-1}(f(x)).$$

Quadratic convergence when Df is locally invertible.

Newton's method for underdetermined systems:

$$f : \mathbb{R}^m \rightarrow \mathbb{R}^n, N_f(x) = Df(x)^\dagger(f(x)).$$

Df^\dagger : **Moore-Penrose pseudo-inverse**.

Quadratic convergence towards a point x_∞ such that $f(x_\infty) = 0$ when Df is locally surjective.

Newton's method

Classical **Newton's method** for $f : \mathbb{R}^n \rightarrow \mathbb{R}^n$

$$N_f(x) = Df(x)^{-1}(f(x)).$$

Quadratic convergence when Df is locally invertible.

Newton's method for underdetermined systems:

$$f : \mathbb{R}^m \rightarrow \mathbb{R}^n, N_f(x) = Df(x)^\dagger(f(x)).$$

Df^\dagger : **Moore-Penrose pseudo-inverse**.

Quadratic convergence towards a point x_∞ such that $f(x_\infty) = 0$ when Df is locally surjective.

If x_0 is the starting point of the iteration, let

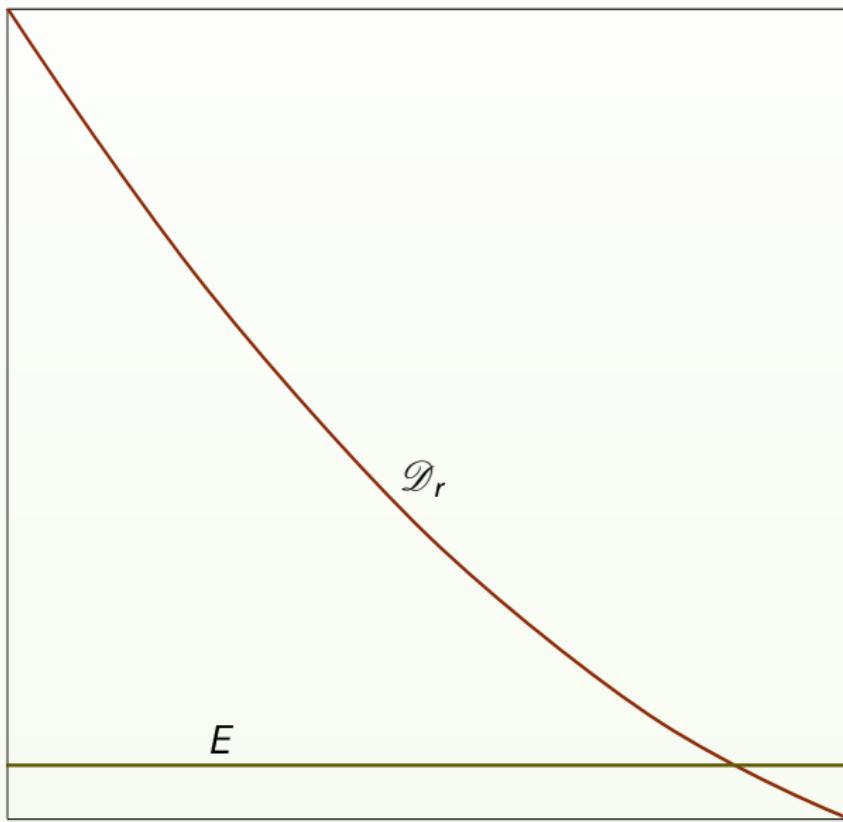
$$\hat{x} = \operatorname{argmin}_{f(y)=0} \|y - x_0\|.$$

Does not converge to the nearest solution \hat{x} , but

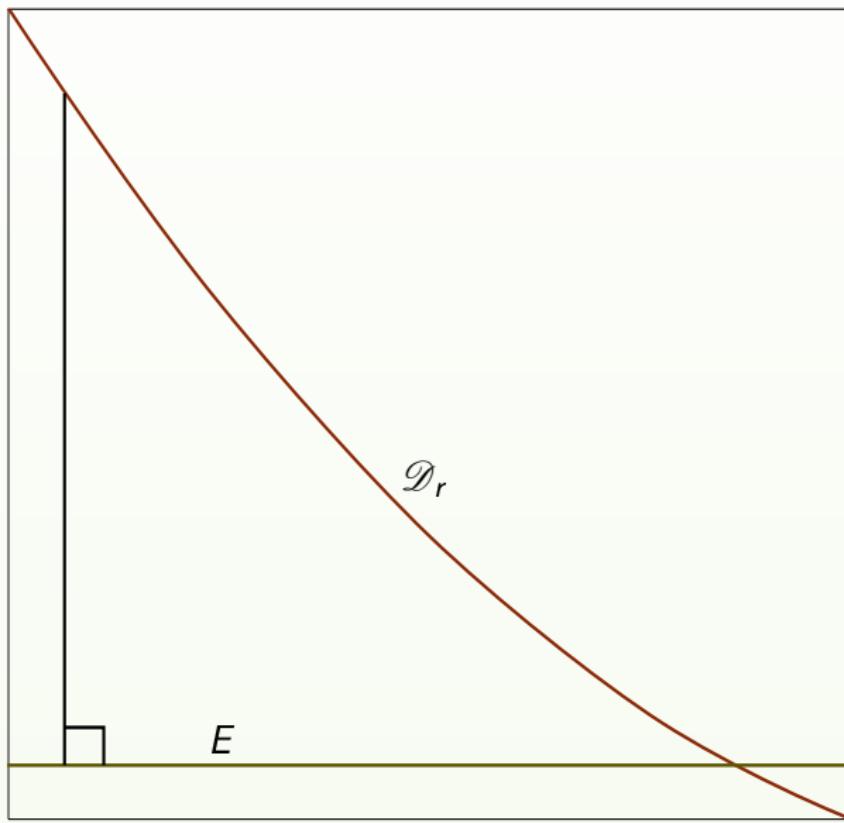
$$\|x_\infty - \hat{x}\| = O(\|x_0 - \hat{x}\|^2).$$

*Ben-Israel 66, Allgower/Georg 90, Beyn 93,
Shub/Smale 96, Dedieu/Shub 00, Dedieu/Kim 02, Dedieu 06*

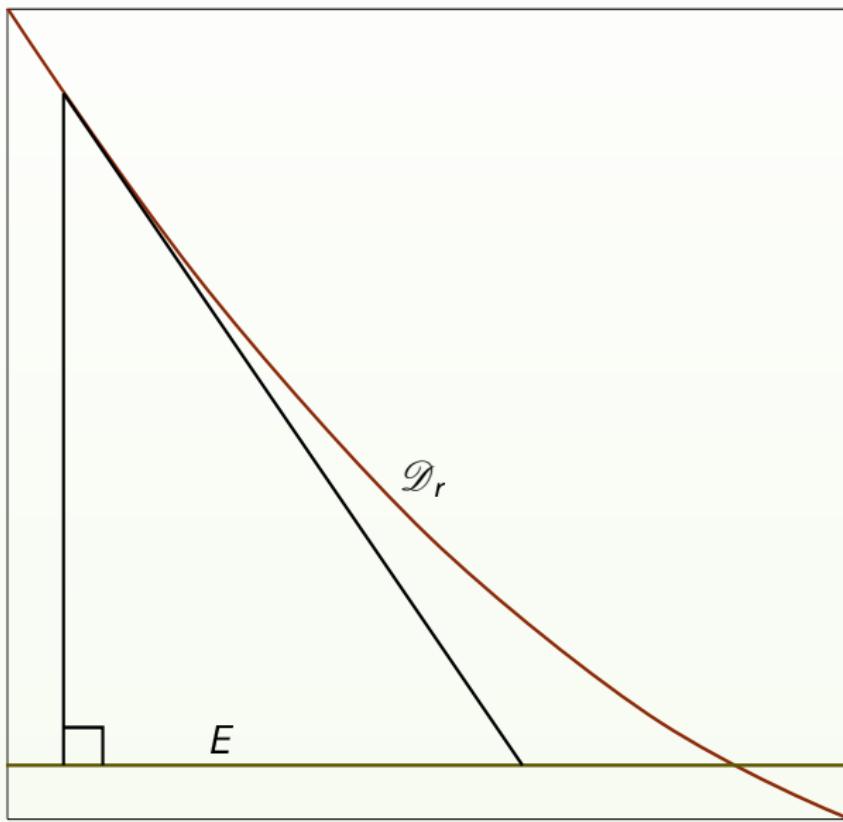
Newton's method



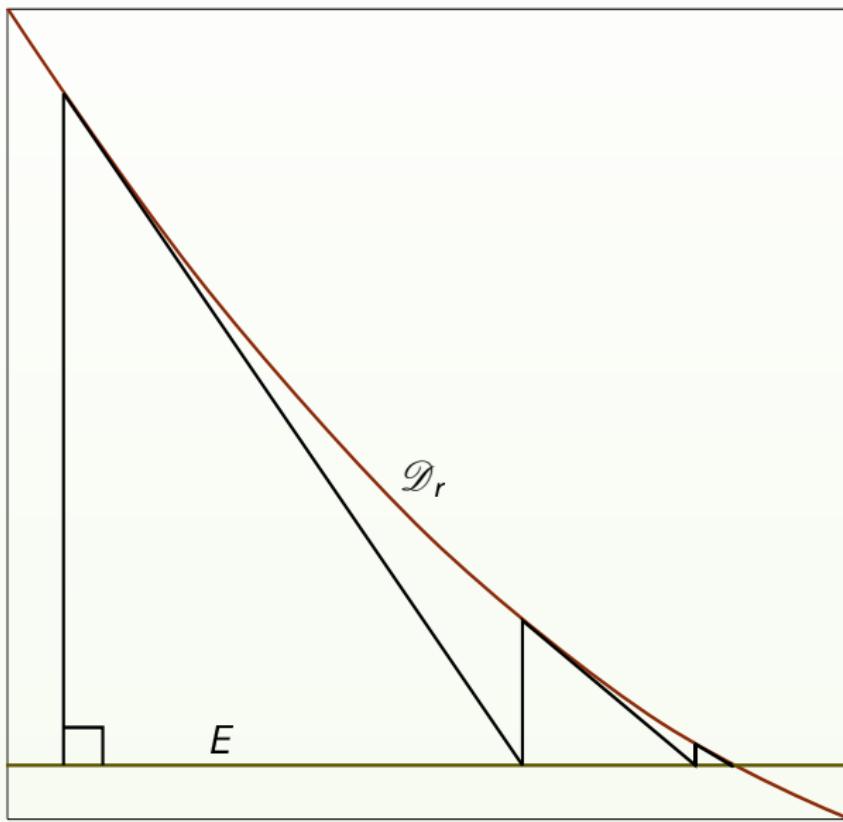
Newton's method

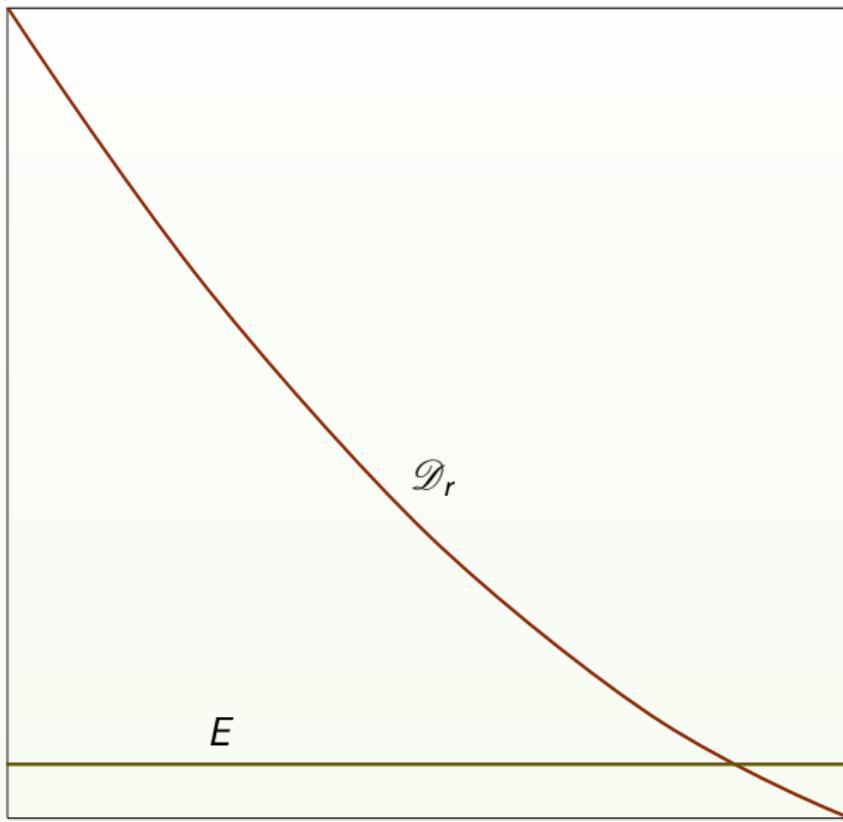


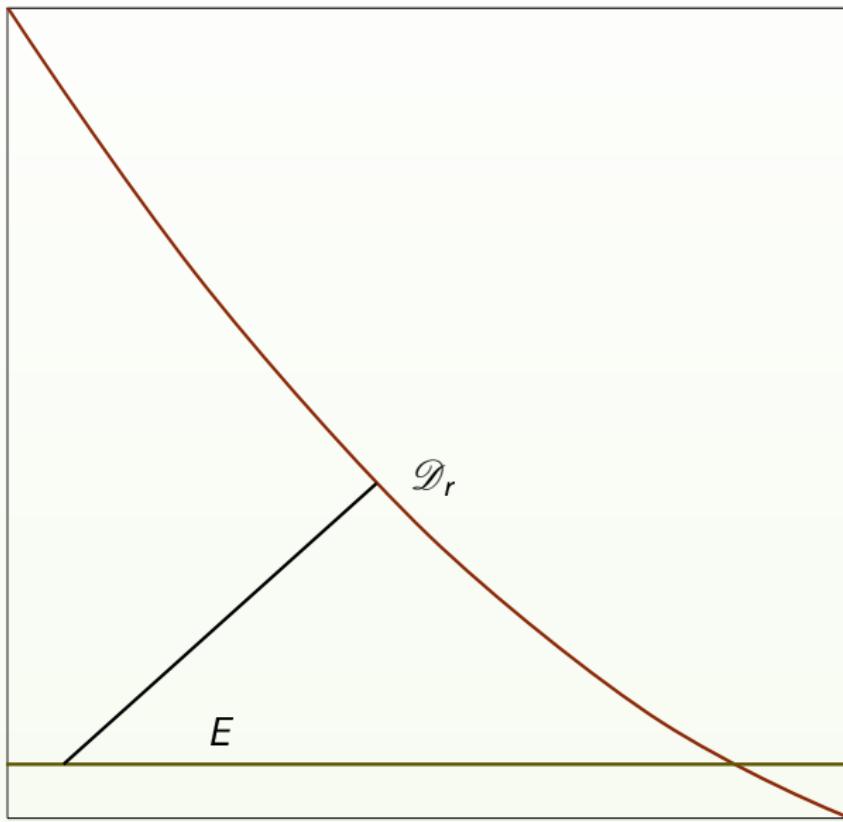
Newton's method

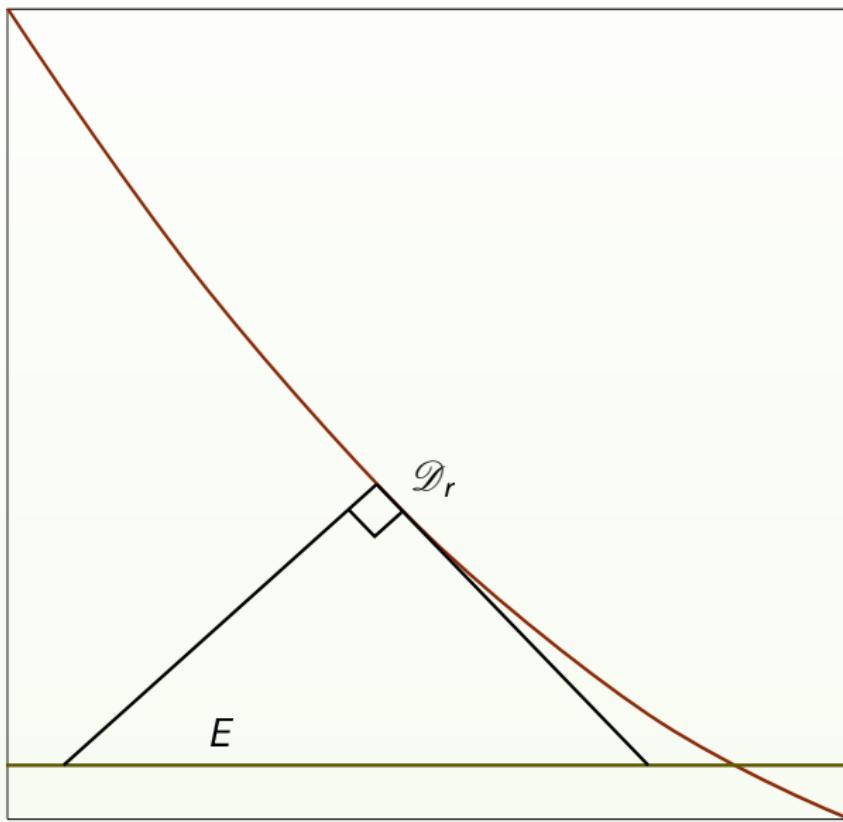


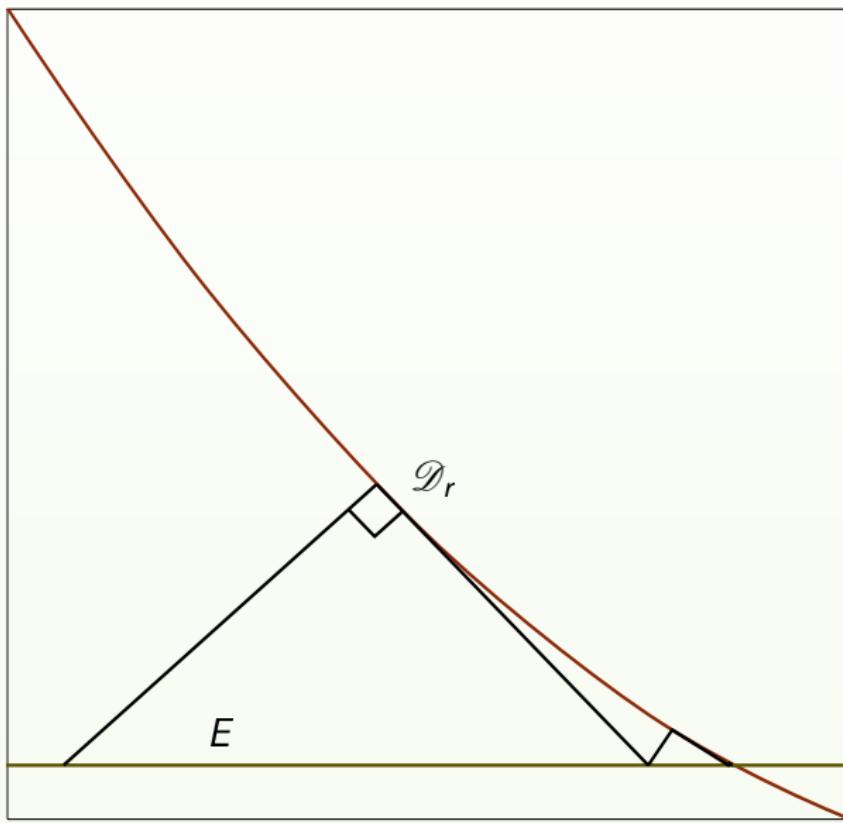
Newton's method











$\overline{\mathcal{D}_r}$: algebraic variety of matrices of rank at most r .

↪ well-studied in algebraic geometry/commutative algebra

Brunn, Conca, Eisenbud, Herzog, Lascoux, Room, Sturmfels, . . .

$\overline{\mathcal{D}_r}$: algebraic variety of matrices of rank at most r .

↪ well-studied in algebraic geometry/commutative algebra

Bruns, Conca, Eisenbud, Herzog, Lascoux, Room, Sturmfels, . . .

Classical theorem

Let M be $p \times q$ matrix of rank r .

Then the **normal space** to \mathcal{D}_r at M is

$$\text{Ker}(M^T) \otimes \text{Ker}(M).$$

Bases of the kernels of M and M^T can be read off from the
Singular Value Decomposition of M .

```
1: procedure NewtonSLRA( $M \in E$ ,  $(E_1, \dots, E_d)$  an orthonormal  
   basis of  $E$ ,  $r \in \mathbb{N}$ )  
2:    $(U, S, V) \leftarrow \text{SVD}(M)$   
3:    $S_r \leftarrow r \times r$  top-left submatrix of  $S$   
4:    $U_r \leftarrow$  first  $r$  columns of  $U$   
5:    $V_r \leftarrow$  first  $r$  columns of  $V$   
6:    $\tilde{M} \leftarrow U_r \cdot S_r \cdot V_r^T$   
7:    $\tilde{u}_1, \dots, \tilde{u}_{p-r} \leftarrow$  last  $p - r$  columns of  $U$   
8:    $\tilde{v}_1, \dots, \tilde{v}_{q-r} \leftarrow$  last  $q - r$  columns of  $V$   
9:   for  $i \in \{1, \dots, p - r\}, j \in \{1, \dots, q - r\}$  do  
10:     $N_{(i-1)(q-r)+j} \leftarrow \tilde{u}_i \cdot \tilde{v}_j^T$   
11:   end for  
12:    $A \leftarrow (\langle N_i, E_j \rangle)_{ij}$   
13:    $b \leftarrow (\langle N_i, \tilde{M} - M \rangle)_i$   
14:   return  $M + [E_1 \dots E_d] \cdot A^\dagger \cdot b$   
15: end procedure
```

Quadratic convergence

For any **smooth** point $\zeta \in \mathcal{D}_r \cap E$ where \mathcal{D}_r and E intersect **transversely**, there exists a small neighborhood $U \ni \zeta$ such that for any input matrix $M_0 \in U$,

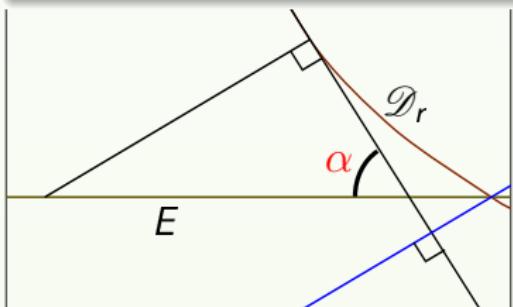
- the sequence of iterates M_1, M_2, \dots **converges quadratically** towards a matrix $M_\infty \in \mathcal{D}_r \cap E$, i.e.
$$\|M_i - M_\infty\| \leq (1/2)^{2^{i-1}} \|M_0 - M_\infty\|$$
- Let \hat{M} be the **nearest solution**; then
$$\|M_\infty - \hat{M}\| = O(\text{dist}(M_0, \mathcal{D}_r \cap E)^2).$$

Rate of convergence

Quadratic convergence

For any **smooth** point $\zeta \in \mathcal{D}_r \cap E$ where \mathcal{D}_r and E intersect **transversely**, there exists a small neighborhood $U \ni \zeta$ such that for any input matrix $M_0 \in U$,

- the sequence of iterates M_1, M_2, \dots **converges quadratically** towards a matrix $M_\infty \in \mathcal{D}_r \cap E$, i.e.
$$\|M_i - M_\infty\| \leq (1/2)^{2^{i-1}} \|M_0 - M_\infty\|$$
- Let \hat{M} be the **nearest solution**; then
$$\|M_\infty - \hat{M}\| = O(\text{dist}(M_0, \mathcal{D}_r \cap E)^2).$$



Sketch of proof:

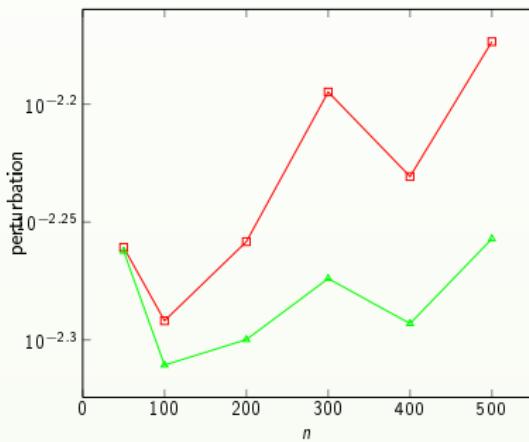
- lower bound for α ;
- Taylor approximation of $\Pi_{\mathcal{D}_r}$;
- manage corrective terms when $\dim(\mathcal{D}_r \cap E) > 0$.

- Combines the **generality of alternating projections** and the **quadratic convergence of Newton's method**.
- Computationally most intensive step: **computing the SVD** (polynomial in p, q at fixed precision).
- Algorithm for SLRA with **proven quadratic rate of convergence**.

Experimental results: approximate GCD/Sylvester matrices

Comparison with GPGCD, *Terui, ISSAC'09.*

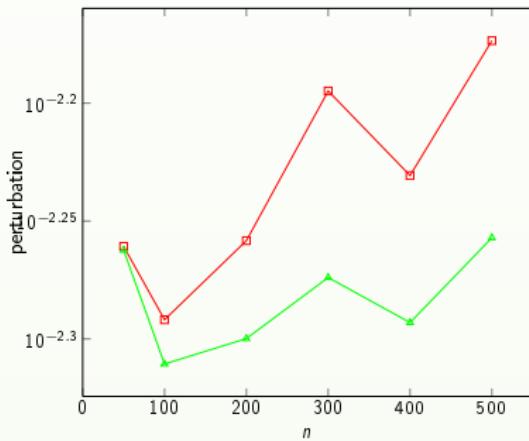
iteration	sizes of iteration steps	
	NewtonSLRA	GPGCD
1	0.9e-1	0.9e-1
2	0.5e-3	0.5e-3
3	0.6e-8	0.2e-5
4	0.1e-17	0.8e-8
5	0.1e-36	0.4e-10



Experimental results: approximate GCD/Sylvester matrices

Comparison with GPGCD, *Terui, ISSAC'09.*

iteration	sizes of iteration steps	
	NewtonSLRA	GPGCD
1	0.9e-1	0.9e-1
2	0.5e-3	0.5e-3
3	0.6e-8	0.2e-5
4	0.1e-17	0.8e-8
5	0.1e-36	0.4e-10



Fast convergence towards $\mathcal{D}_r \cap E$

~ starting point for a certified **Gauss-Newton iteration**

Yakoubsohn/Masmoudi/Chèze/Auroux 06

Linear sections of determinantal varieties

rich **structure** with a lot of facets
(numeric/symbolic, finite fields/characteristic 0, real solutions)
which appears in many applications.

- Low-rank matrix completion, Hankel matrices.
- **Algebraic** properties of special linear subspaces
~~ Euclidean distance degree, *Ottaviani/S./Sturmfels '13*.
- **Certification** of NewtonSLRA *a la Dedieu*: α, γ theorems?

Linear sections of determinantal varieties

rich **structure** with a lot of facets
(numeric/symbolic, finite fields/characteristic 0, real solutions)
which appears in many applications.

- Low-rank matrix completion, Hankel matrices.
- **Algebraic** properties of special linear subspaces
~~ Euclidean distance degree, *Ottaviani/S./Sturmfels '13.*
- **Certification** of NewtonSLRA *a la Dedieu*: α, γ theorems?

Thank you!

Application to approximate GCD

Approximate GCD

Let $m, n, d \in \mathbb{N}$, $f, g \in \mathbb{R}[x]$ with $\deg(f) = m, \deg(g) = n$.

Find $f^*, g^* \in \mathbb{R}[x]$, $\deg(f^*) = m, \deg(g^*) = n$ such that

$$\deg(\text{GCD}(f^*, g^*)) \geq d$$

and (f^*, g^*) are close to (f, g) .

- needs a **distance** on the pairs (f, g) :

$$\left\| \left(\sum_{i=0}^m f_i x^i, \sum_{j=0}^n g_j x^j \right) \right\|^2 = \sum_{i=0}^m f_i^2 + \sum_{j=0}^n g_j^2.$$

- What does “close” mean
 - ~ quasi-GCD, Schönage 85
 - ~ ε -GCD, Emiris/Galligo/Lombardi 97, Zeng/Dayton 04, Bini/Boito 06-09
 - ~ nearest pair for a given norm, Karmarkar/Lakshman 98, Kaltofen/Zhi/Yang 05-08, Terui 09

Matrix Completion

Unknown matrix of **rank r** :

$$\begin{bmatrix} ? & ? & ? & ? \\ ? & ? & ? & ? \\ ? & ? & ? & ? \\ ? & ? & ? & ? \end{bmatrix}$$

Uncover **m entries** at random.

Matrix Completion

Unknown matrix of **rank r** :

$$\begin{bmatrix} ? & ? & ? & ? \\ ? & ? & ? & ? \\ ? & ? & ? & ? \\ ? & ? & ? & ? \end{bmatrix}$$

Uncover **m entries** at random.

Matrix Completion

Unknown matrix of **rank r**:

$$\begin{bmatrix} ? & \color{red}{4} & ? & ? \\ ? & ? & ? & ? \\ ? & ? & ? & ? \\ ? & ? & ? & ? \end{bmatrix}$$

Uncover ***m* entries** at random.

Matrix Completion

Unknown matrix of **rank r** :

$$\begin{bmatrix} ? & \color{red}{4} & ? & ? \\ ? & ? & ? & ? \\ \color{red}{1} & ? & ? & ? \\ ? & ? & ? & ? \end{bmatrix}$$

Uncover **m entries** at random.

Matrix Completion

Unknown matrix of **rank r**:

$$\begin{bmatrix} ? & \color{red}{4} & ? & ? \\ ? & ? & \color{red}{7} & ? \\ \color{red}{1} & ? & ? & ? \\ ? & ? & ? & ? \end{bmatrix}$$

Uncover ***m* entries** at random.

Matrix Completion

Unknown matrix of **rank r** :

$$\begin{bmatrix} ? & \color{red}{4} & ? & ? \\ ? & ? & \color{red}{7} & ? \\ \color{red}{1} & ? & \color{red}{9} & ? \\ ? & ? & ? & ? \end{bmatrix}$$

Uncover **m entries** at random.

Matrix Completion

Unknown matrix of **rank r**:

$$\begin{bmatrix} ? & \color{red}{4} & ? & ? \\ ? & ? & \color{red}{7} & ? \\ \color{red}{1} & ? & \color{red}{9} & ? \\ ? & ? & ? & \color{red}{7} \end{bmatrix}$$

Uncover ***m* entries** at random.

Matrix Completion

Unknown matrix of **rank r**:

$$\begin{bmatrix} ? & \color{red}{4} & ? & ? \\ ? & ? & \color{red}{7} & ? \\ \color{red}{1} & ? & \color{red}{9} & ? \\ ? & ? & ? & \color{red}{7} \end{bmatrix}$$

Uncover ***m* entries** at random.

How many entries do we need? How to reconstruct the matrix?

Matrix Completion

Unknown matrix of **rank r**:

$$\begin{bmatrix} ? & \textcolor{red}{4} & ? & ? \\ ? & ? & \textcolor{red}{7} & ? \\ \textcolor{red}{1} & ? & \textcolor{red}{9} & ? \\ ? & ? & ? & \textcolor{red}{7} \end{bmatrix}$$

Uncover ***m* entries** at random.

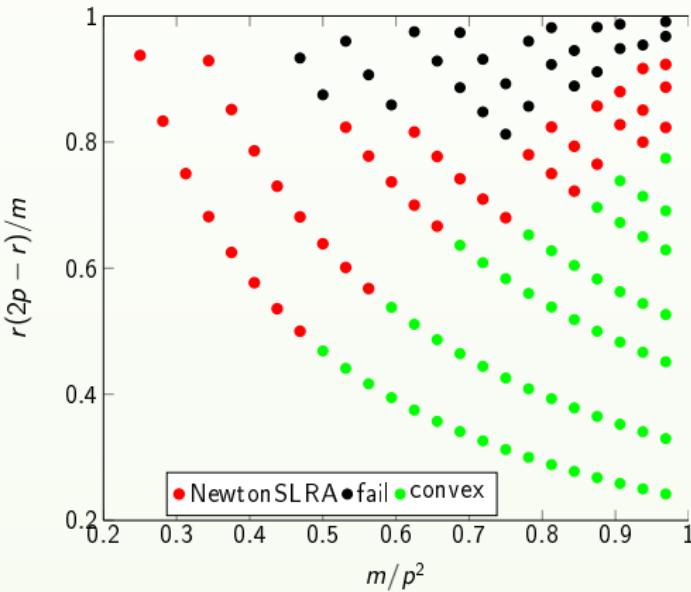
How many entries do we need? How to reconstruct the matrix?

- Alternating minimization, *Jain, Netrapalli, Sanghavi, 12*
- Riemannian optimization,
Absil/Amodei/Meyer 12, Vandereycken 12
- Convex relaxation, *Candes, Tao, Plan, Recht, 09-13*

Experimental results

Overdetermined SLRA problems

Transversality assumption do not hold \rightsquigarrow no quadratic convergence.
Square matrix of size $p = 40$



An algebraic approach to SLRA

The Euclidean distance degree

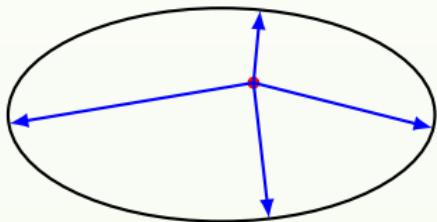
Draisma/Horobet/Ottaviani/Sturmfels/Thomas 13

$V \in \mathbb{C}^n$ an algebraic variety, $\mathbf{u} \in \mathbb{C}^n$ a generic point. The

EDdegree of V is the number of **complex critical points** of the function

$$\lambda_1(x_1 - u_1)^2 + \cdots + \lambda_n(x_n - u_n)^2$$

on the smooth locus of V .



Nearest solution of SLRA:

critical point of the distance function on a **linear section of a determinantal variety** $\mathcal{D}_r \cap E$.

$$\text{EDdegree}(\text{ellipse}) = 4.$$

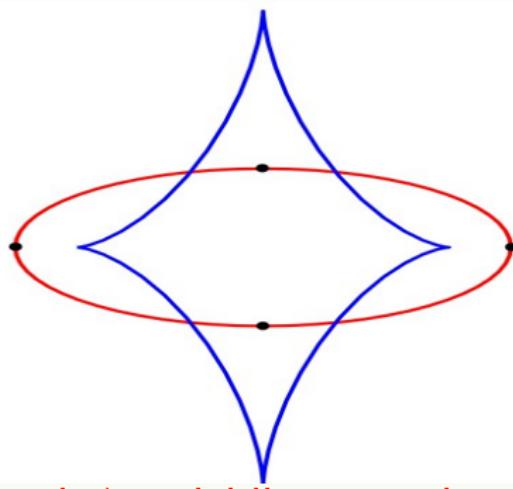
Proposition (Draisma/Horobet/Ottaviani/Sturmfels/Thomas)

Under **transversality assumptions** with a special quadric and for generic weights, the **EDdegree** of a projective variety is the sum of the degrees of its **polar classes**.

How many **real solutions**?

Important information for numerical algorithms.

~~~ **ED discriminant**



What happens if the variety is a **generic/special linear section of a determinantal variety**?